

**PULSE METER  
MP5W SERIES**

**M A N U A L**



Thank you very much for selecting Autonics products.  
For your safety, please read the following before using.

**Caution for your safety**

- ※Please keep these instructions and review them before using this unit.
- ※Please observe the cautions that follow:
  - Warning** Serious injury may result if instructions are not followed.
  - Caution** Product may be damaged, or injury may result if instructions are not followed.
- ※The following is an explanation of the symbols used in the operation manual.
  - ⚠caution: Injury or danger may occur under special conditions.

**Warning**

- In case of using this unit with machineries(Nuclear power control, medical equipment, vehicle, train, airplane, combustion apparatus, entertainment or safety device etc), it requires installing fall-safe device, or contact us for information on type required.**  
It may result in serious damage, fire or human injury.
- It must be mounted on panel.**  
It may give an electric shock.
- Do not repair or check up when power on.**  
It may give an electric shock.
- Do not disassemble and modify this unit, when it requires. If needs, please contact us.**  
It may give an electric shock and cause a fire.
- Please check the number of terminal when connect power line or measuring input.**  
It may cause a fire.

**Caution**

- This unit shall not be used outdoors.**  
It might shorten the life cycle of the product or give an electric shock.
- When wire connection for power input and measuring input, the tightening strength for screw bolt on terminal block should be over than 0.74N·m ~ 0.90N·m.**  
It may result in malfunction or fire due to contact failure.
- Please observe specification rating.**  
It might shorten the life cycle of the product and cause a fire.
- Do not use the load beyond rated switching capacity of Relay contact.**  
It may cause insulation failure, contact melt, contact failure, relay broken, fire etc.
- In cleaning the unit, do not use water or an oil-based detergent.**  
It might cause an electric shock or fire that will result in damage to this product.
- Do not use this unit at place where there are flammable or explosive gas, humidity, direct ray the sun, radiant heat, vibration, impact etc.**  
It may cause a fire or explosion.
- Do not inflow dust or wire dregs into inside of this unit.**  
It may cause a fire or mechanical trouble.
- Please connect properly after checking the polarity of measuring terminals.**  
It may cause a fire or explosion.

※The above specification are changeable without notice anytime.

**Ordering information**

<b>MP 5 W - 4 N</b>		
MP	Main output (Comparative value output)	Sub output (Display value output)
5	Indicator	-
W	Relay five-stage(HH, H, GO, L, LL)	-
4	Relay three-stage(H, GO, L)	-
N	NPN open collector quintuple output	BCD Dynamic
	PNP open collector quintuple output	BCD Dynamic
	NPN open collector quintuple output	PV transmission output (DC4-50mA)
	PNP open collector quintuple output	PV transmission output (DC4-50mA)
	NPN open collector quintuple output	Low speed serial output
	PNP open collector quintuple output	Low speed serial output
	NPN open collector quintuple output	RS485 communication
	PNP open collector quintuple output	RS485 communication
	Power supply	4 100-240VAC 50/60Hz
	Size	W DIN W96 × H48mm
	Digit	5 99999(5 Digit)
	Item	MP Pulse meter

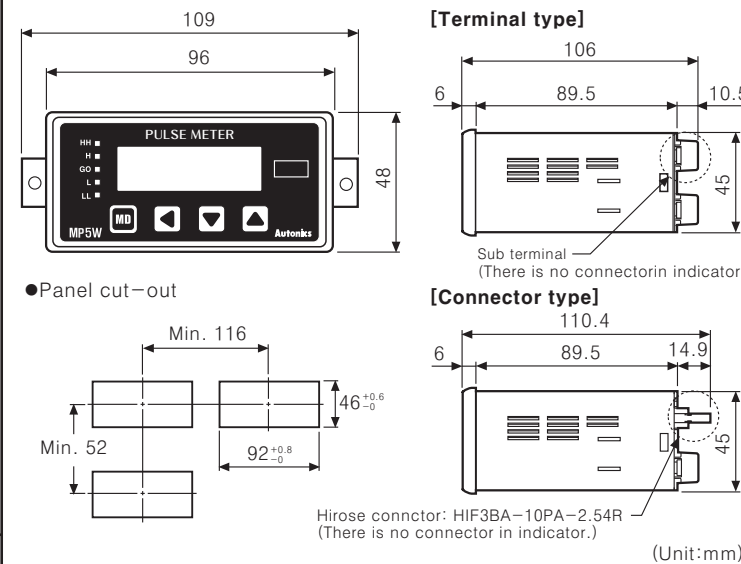
※PNP open collector output:Option

**Specifications**

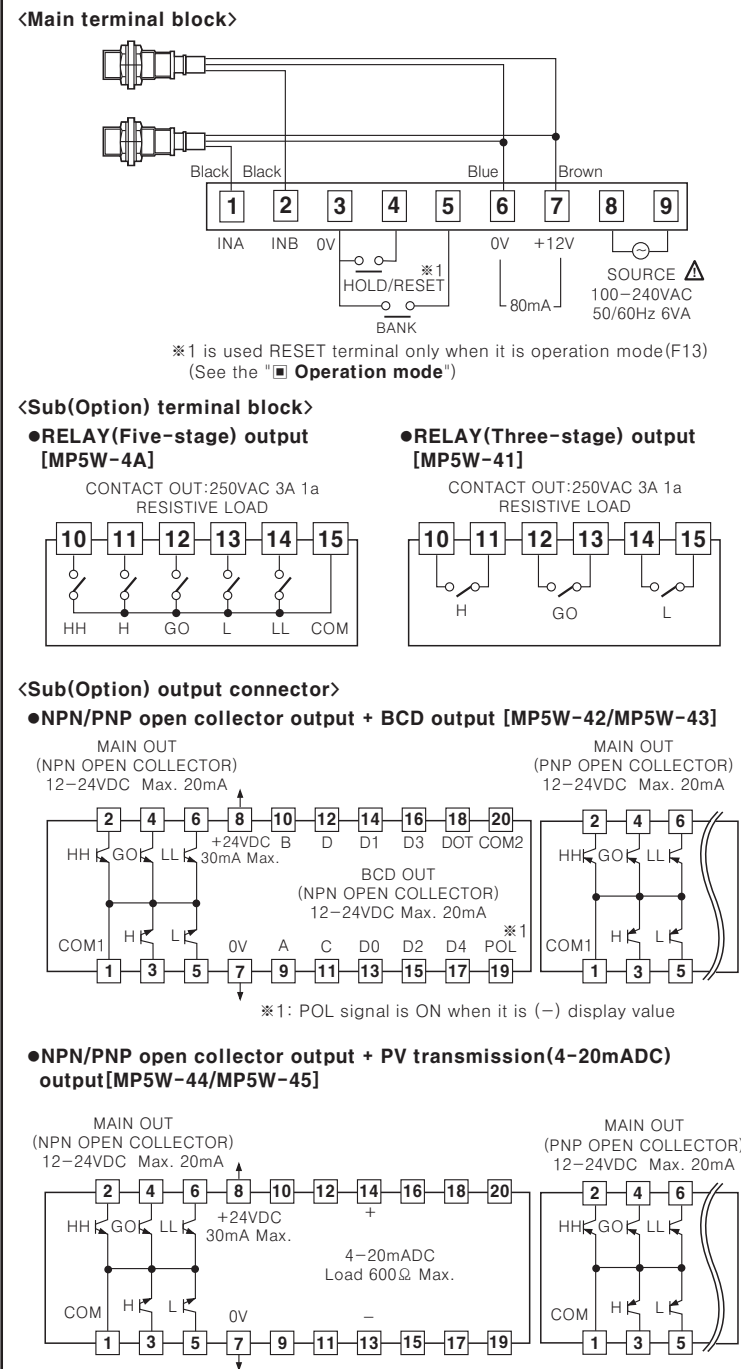
Series	<b>MP5W</b>	
Display method	7 Segment LED (Zero Blanking)	
Character size	W7 × H14mm	
Max. indication	5digit (-19999 to 99999)	
Power supply	100-240VAC 50/60Hz	
Allowable operation voltage	90 to 110% of rated voltage	
Power consumption	Approx. Max. 6VA	
Power for external sensor	12VDC ±10%, 80mA	
Input frequency	<ul style="list-style-type: none"> <li>Solid state input : Max. 50kHz(Pulse width:Min. 10<math>\mu</math>s)</li> <li>Contact input : Max. 45Hz(Pulse width:Min. 11ms)</li> </ul>	
Input level	[Voltage input] High:4.5-24VDC, Low:0-1VDC, [No-voltage input] Residual voltage:Max. 1V	
Measuring range	<ul style="list-style-type: none"> <li>Mode F1, F2, F7, F8, F9, F10 : 0.005Hz to 50kHz</li> <li>Mode F3 : 0.02s to 3,200s</li> <li>Mode F4, F5, F6 : 0.01s to 3,200s</li> <li>Mode F11, F12, F13 : 0 to 4 × 10<sup>9</sup> Count</li> </ul>	
Measuring accuracy (23 ± 5°C)	<ul style="list-style-type: none"> <li>Mode F1, F2, F7, F8, F9, F10 : F.S. ±0.05% rdg ±1Digit</li> <li>Mode F3, F4, F5, F6 : F.S. ±0.01% rdg ±1Digit</li> </ul>	
Display accuracy	0.05 / 0.5 / 1 / 2 / 4 / 8sec.(The same as update output cycle)	
Operation mode	Number of revolution/Speed/Frequency(F1), Passing speed(F2), Cycle(F3), Passing time(F4), Time width(F5), Time difference (F6), Absolute rate(F7), Error ratio(F8), Density(F9), Error(F10), Length measurement(F11), Interval(F12), Integration(F13)	
Prescale function	Direct input method(0.0001 × 10 <sup>-9</sup> to 9.9999 × 10 <sup>9</sup> )	
Hysteresis	0 to 9999 *1	
Other functions	<ul style="list-style-type: none"> <li>Lock setting function</li> <li>Auto-Zero time setting function</li> <li>Current output range selection(Current output type only)</li> <li>Comparative output function(HH, H, GO, L, LL)</li> <li>Deviation memory function(F output mode applied only)</li> <li>Peak value monitoring value</li> <li>Remote/Local switching function(Communication output type only)</li> <li>Data Bank switching function</li> <li>Memory protection function(Mode F13 applied only)</li> <li>Monitoring delay function</li> <li>Time unit selection function</li> </ul>	
Main output	Triple/Quintuple relay	250VAC 3A resistive load 3a
	NPN open collector quintuple output	12-24VDC 30mA Max.
	PNP open collector quintuple output	12-24VDC 30mA Max.
Sub output	BCD Dynamic	NPN open collector 12-24VDC 20mA Max.
	Low speed serial output	NPN open collector 12-24VDC 20mA Max.
	PV transmission	DC4-20mA Load 600 $\Omega$ Max.(Response time: Max. 800ms)
	RS485 com.	32 channels, Mutual direction communication function
Memory	Non-volatile memory(Input times : 100,000 times)	
Insulation resistance	Min. 100M $\Omega$ (at 500VDC megger) between terminal and case	
Dielectric strength	2000VAC 60Hz 1minute(Between terminals of AC power and case, Between terminals of AC power and measuring terminals)	
Impulse noise strength	±2000V the square wave noise(pulse width:1 $\mu$ s) by the noise simulator	
Vibration	Mechanical	0.75mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hour
	Malfunction	0.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 10 minutes
Shock	Mechanical	300m/s <sup>2</sup> (Approx. 30G) 3 times at X, Y, Z direction
	Malfunction	100m/s <sup>2</sup> (Approx. 10G) 3 times at X, Y, Z direction
Relay life cycle	Mechanical	Min. 10,000,000 operations
	Electrical	Min. 100,000 times at 250VAC 3A(resistive load)
Environment	Ambient temperature	-10 to 50°C, Storage temperature: -20 to 60°C
	Ambient humidity	35 to 85%RH, Storage humidity: 35 to 85%RH
Unit weight	Approx. 230g	

\*Condition for use in environment is no freezing or condensation.  
\*1: The hysteresis setting range is changed by the setting position of decimal point.

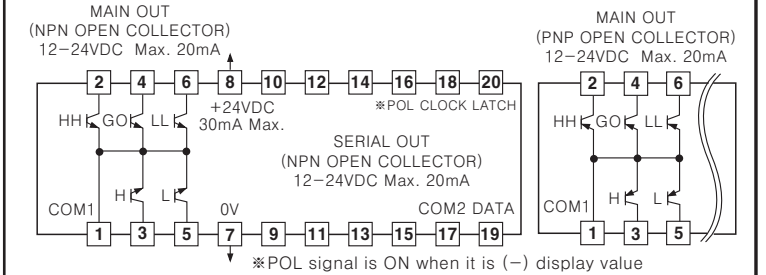
**Dimensions**



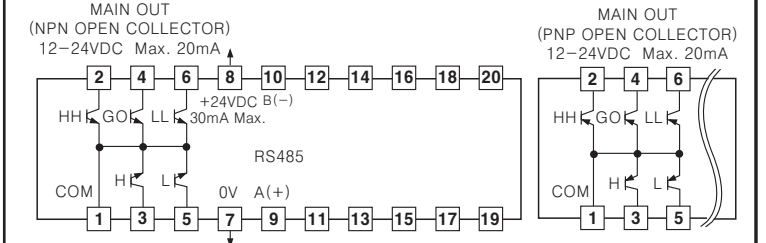
**Connections**



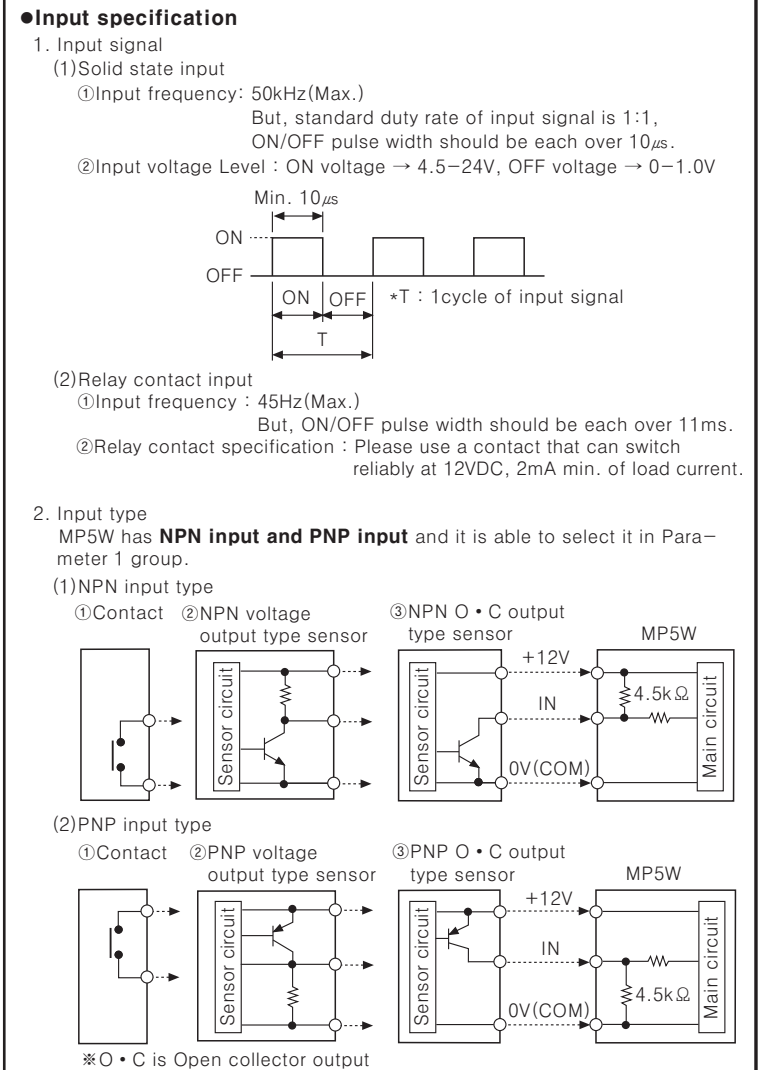
**NPN/PNP open collector output + Low speed serial output [MP5W-46/MP5W-47]**



**NPN /PNP open collector output + RS485 communication output [MP5W-48/MP5W-49]**



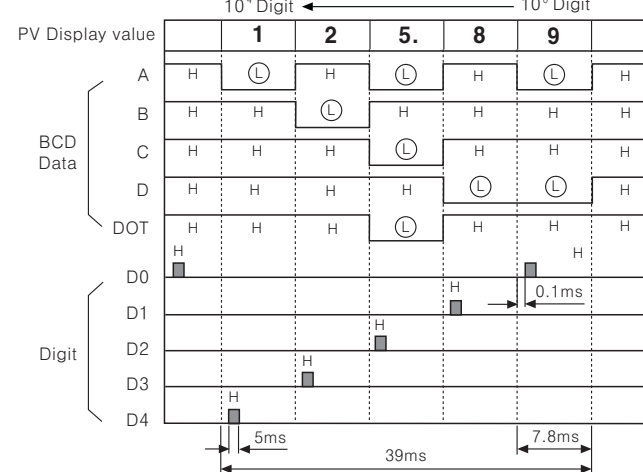
**Input · Output**



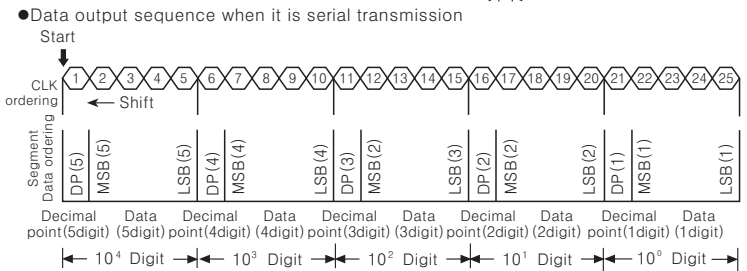
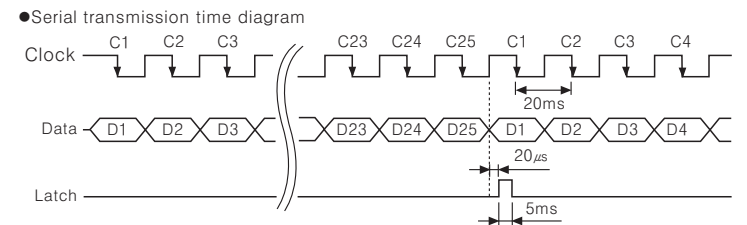
**Output specification**

- Relay output
  - Output : Comparative or alarm output(See the "Output mode")
  - Output method : Relay
  - Contact capacity : 250VAC 3A resistive load
  - Life cycle : Mechanical-20million times(Switch times 180 times/min.)  
Electrical-Min.100,000 times(3A 250VAC at resistive load)  
(Switch times : 20 times/min.)
- TR output
  - Output : Comparative or alarm output(See the "Output mode")
  - Output method : NPN / PNP Open collector
  - Rated load voltage : 12-24VDC
  - Max. load current : 20mA

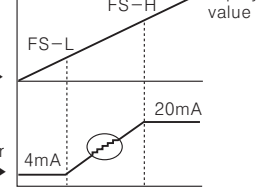
3. BCD Dynamic output
- Output : Display value
  - Output signal : BCD Data(A, B, C, D, DOT) ← A: Lowest bit, Dot: Highest bit  
Digit Data(D0, D1, D2, D3, D4) ← D0: Lowest digit, D4: Highest digit
  - Output type : NPN Open Collector
  - Rated load voltage : 12-24VDC
  - Max. load current : 20mA
- Ex) When display value is 125.89



4. Low speed serial output
- Output : Display value
  - Output signal : Clock, Data, Latch
  - Clock cycle : 50Hz
  - Output Clock bit : 25 bit
  - Output Data bit : 25 bit
  - Output form: NPN Open Collector
  - Rated load voltage : 12-24VDC
  - Max. load current : 20mA



5. PV transmission output(4-20mADC)
- Application : To transmit the measured value
  - Function : This function is to transmit 4-20mADC converted from measured display value between High limit output(FS-H) and Low limit(FS-L).
  - Range of High/Low limit output setting
    - High limit setting range(FS-H): From min. to max within range of measurement
    - Low limit setting range(FS-L): From min. to max within range of measurement (FS-H should be over "1" bigger than FS-L)
  - Resistive load : Max. 600Ω
  - Resolution : 8000 division

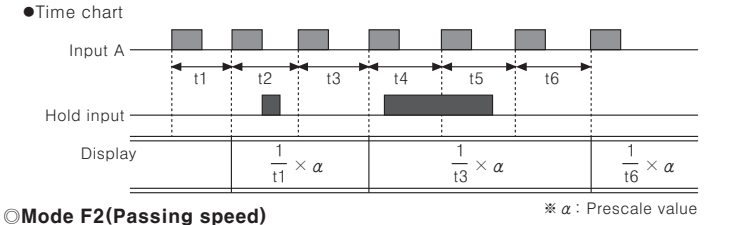
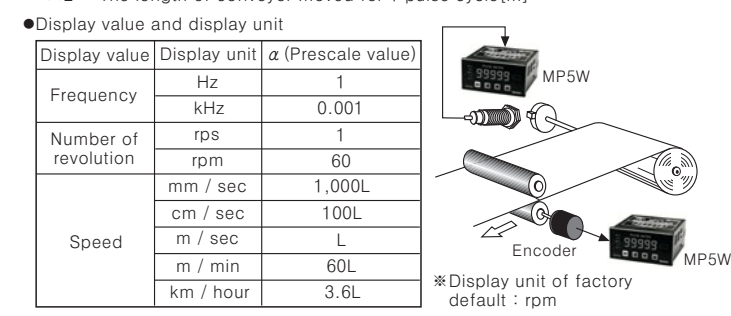


6. RS485 communication output
- Address : 0 ~ 99 address(32 channel)
  - Transmission speed(Baud rate) : 2400/4800/9600 bps
  - Transmission code : ASCII
  - Parity Bit : No
  - Data Bit : 8 Bit
  - Stop Bit : 1 Bit
  - Communication items
    - MP5W ← PC : Comparative value of each bank data, Prescale value and Peak value, RESET control
    - MP5W → PC : Comparative value of each bank data, Prescale value and Peak value, Display value

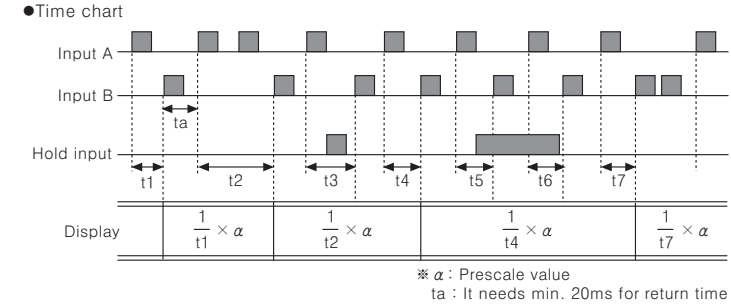
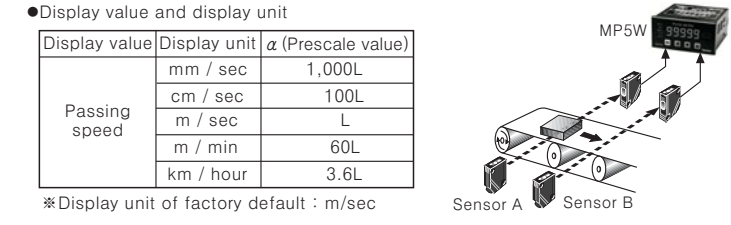
## Operation mode

- Select operation mode from **mode**(mode) of Parameter 1 group.
- There are 13 kinds of operation mode in this unit.

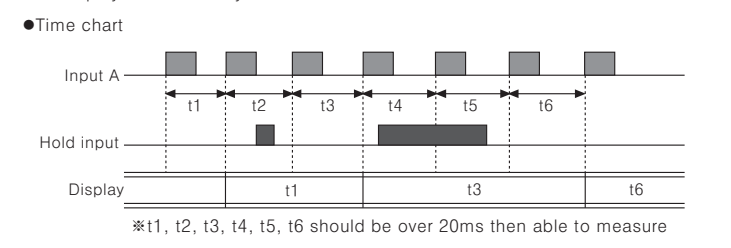
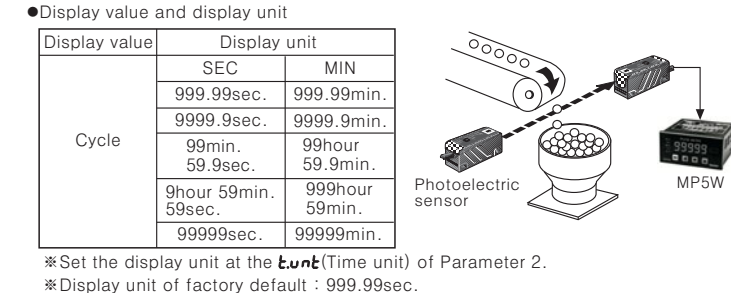
- **Mode F1(Frequency/Number of revolution/Speed)**  
This mode is to display calculated frequency or number of revolution, speed by measuring frequency of Input A.
- Frequency(Hz) =  $f \times \alpha$  ( $\alpha = 1[\text{sec}]$ )
  - Number of revolution(rpm) =  $f \times \alpha$  ( $\alpha = 60[\text{sec}]$ )
  - Speed(m/min) =  $f \times \alpha$  ( $\alpha = 60L[\text{sec}]$ )
- \* L = The length of conveyor moved for 1 pulse cycle[m]



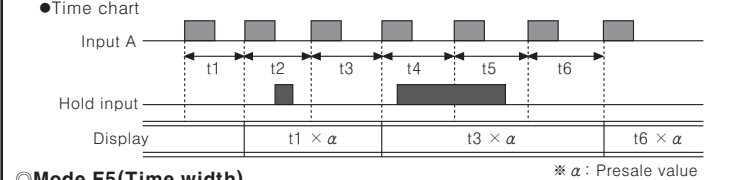
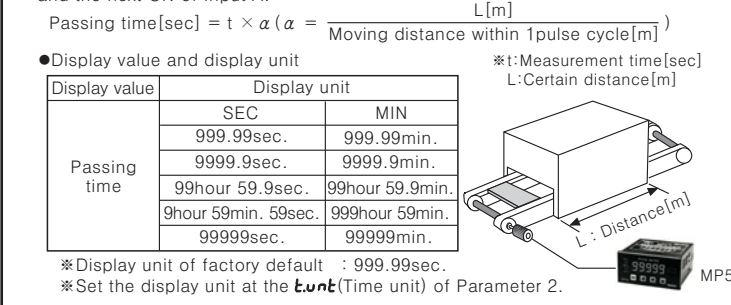
- **Mode F2(Passing speed)**  
It displays the passing speed between ON of input A and ON of input B.
- Passing speed(V) =  $f \times \alpha$  ( $\alpha = L[\text{m}]$ )
- \* f : This is reciprocal number of the time between ON of input A and ON of input B  
L : The distance between input A and input B[m]



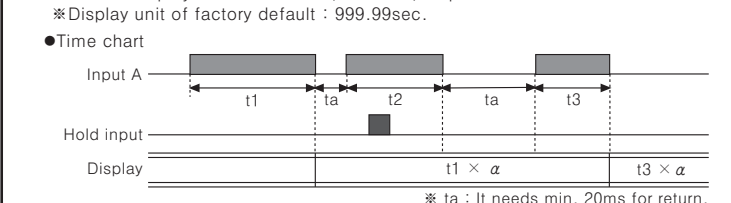
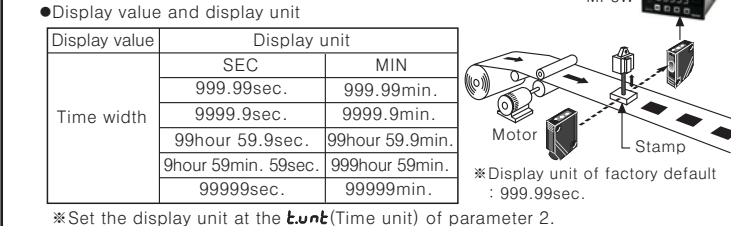
- **Mode F3(Cycle)**  
It displays the time from when input A is ON to the next ON of input A.
- Cycle(T) = t
- \* t : Measurement time[sec]



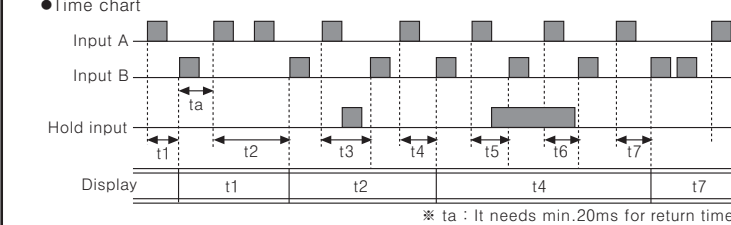
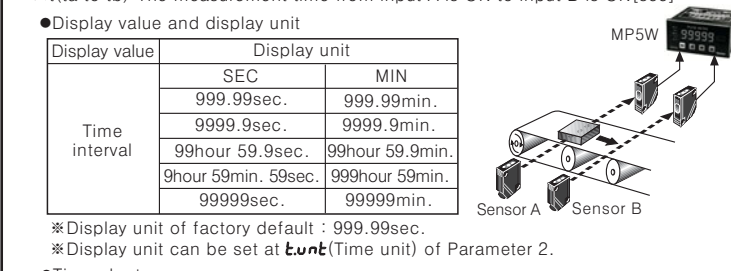
- **Mode F4(Passing time)**  
It displays the passing time of certain distance as measuring the time between ON and the next ON of Input A.
- Passing time[sec] =  $t \times \alpha$  ( $\alpha = \frac{L[\text{m}]}{\text{Moving distance within 1 pulse cycle}[\text{m}]}$ )



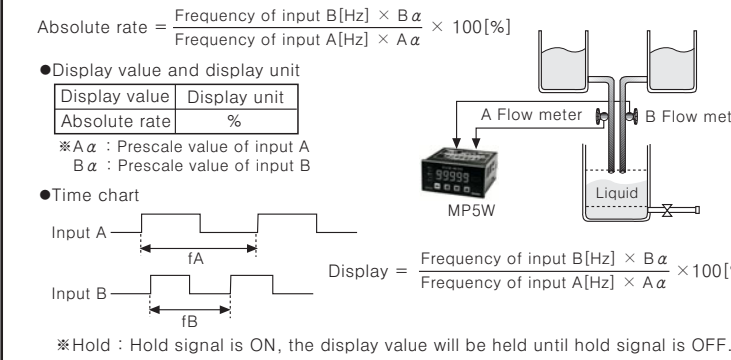
- **Mode F5(Time width)**  
It displays the ON time of input A.
- Time width[T] = t
- \* t : ON measurement time of input A[sec]



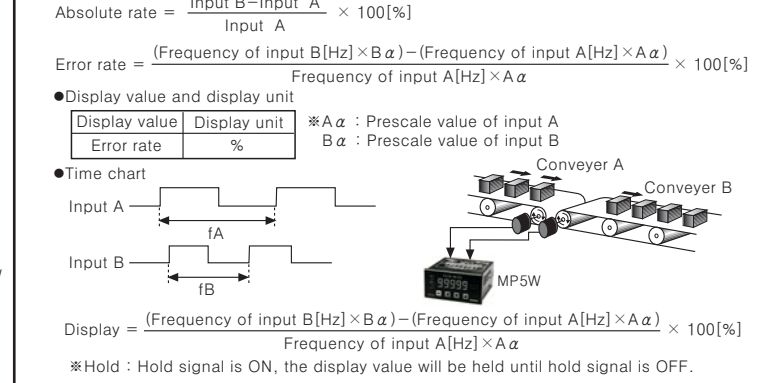
- **Mode F6(Time interval)**  
It displays the time from input A is ON to input B is ON.
- Time difference(T) = t(t\_a to t\_b)
- \* t(t\_a to t\_b): The measurement time from input A is ON to input B is ON[sec]



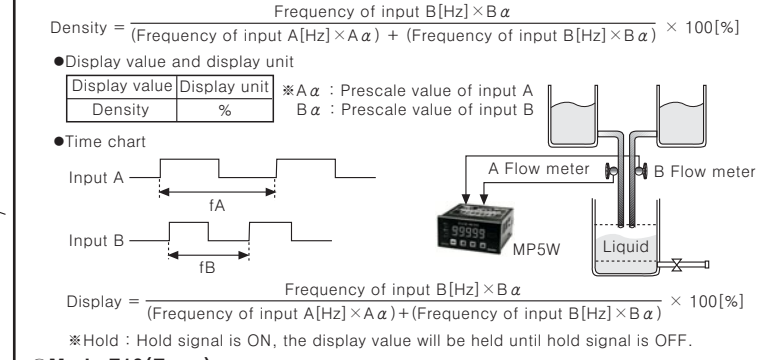
- **Mode F7(Absolute rate)**  
It displays how many percentage(%) faster or late, speed, volume etc. of Input B against input A
- Absolute rate =  $(\text{Input B} / \text{Input A}) \times 100\%$
- Absolute rate =  $\frac{\text{Frequency of input B}[\text{Hz}] \times B\alpha}{\text{Frequency of input A}[\text{Hz}] \times A\alpha} \times 100\%$



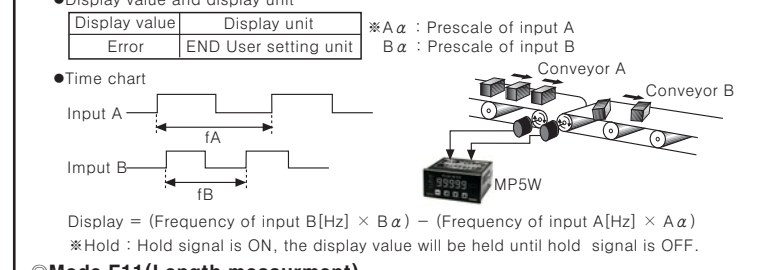
- **Mode F8(Error ratio)**  
It displays how many percentage(%) faster or late of Input B against Input A.
- Absolute rate =  $\frac{\text{Input B} - \text{Input A}}{\text{Input A}} \times 100\%$
- Error rate =  $\frac{(\text{Frequency of input B}[\text{Hz}] \times B\alpha) - (\text{Frequency of input A}[\text{Hz}] \times A\alpha)}{\text{Frequency of input A}[\text{Hz}] \times A\alpha} \times 100\%$



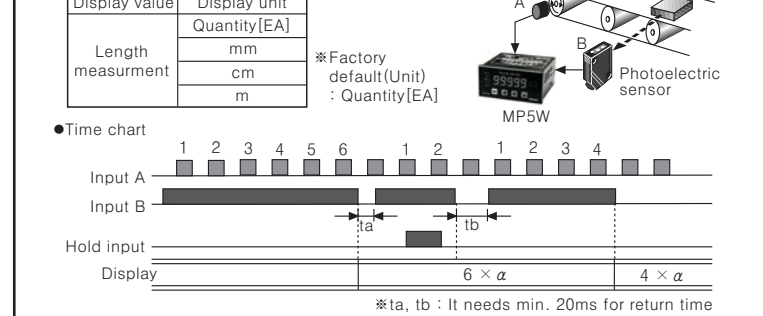
- **Mode F9(Density)**  
It displays the density rate of input B against total sum of input A and input B.
- Density =  $\frac{\text{Input B}}{\text{Input A} + \text{Input B}} \times 100\%$
- Density =  $\frac{\text{Frequency of input B}[\text{Hz}] \times B\alpha}{(\text{Frequency of input A}[\text{Hz}] \times A\alpha) + (\text{Frequency of input B}[\text{Hz}] \times B\alpha)} \times 100\%$



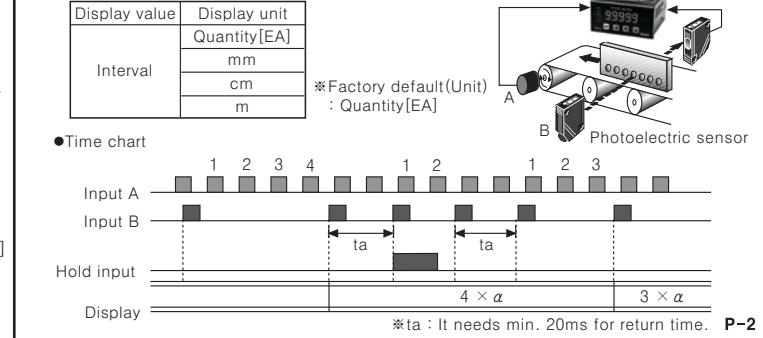
- **Mode F10(Error)**  
It displays the error between standard Input A and comparing Input B.
- Error = Input B - Input A
- Error =  $(\text{Frequency of input B}[\text{Hz}] \times B\alpha) - (\text{Frequency of input A}[\text{Hz}] \times A\alpha)$



- **Mode F11(Length measurement)**  
It displays the number of Input A pulse while Input B is ON.
- Length measurement =  $P \times \alpha$  (\* P : Number of input A pulse,  $\alpha$  : Prescale value)



- **Mode F12(Interval)**  
It displays the number of Input A pulse from Input B is ON to the time Input B is ON next.
- Interval =  $P \times \alpha$  (\* P : Number of input A pulse,  $\alpha$  : Prescale value)





**Mode F13(Integration)**

It displays the counting value against pulses of Input A.  
Integration = P × α

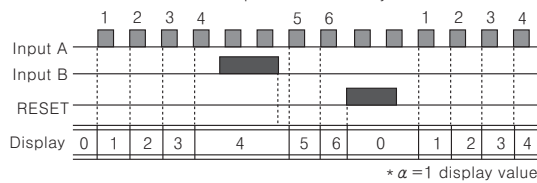
\*P : Pulse number of input A, α : Prescale value

●Display value and display unit

Display value	Display unit
Integration	Quantity[EA]

●Operation and Time chart

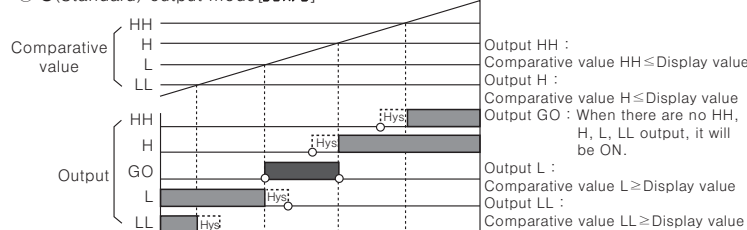
①It counts the number of input A pulse.  
②As input B is an enable input signal it stops the counting and display value of input A when it is ON and then it counts input A continuously when it is OFF.



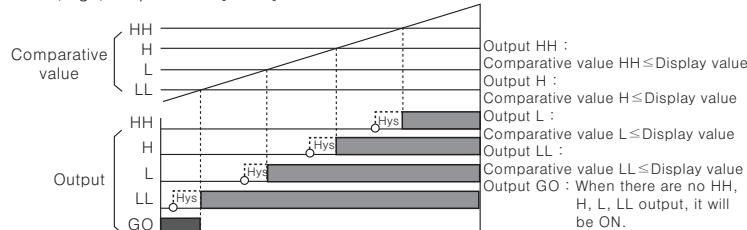
**Output mode**

- Select output mode in **out-t** (output type) of Parameter1 group.
- There are 5 stages output(HH, H, GO, L, LL) and 3 stage output(H, GO, L).
- There are 6 kinds of output mode such as S(Standard) output mode, H(High) output mode, L(Low) output mode, B(Block) output mode, I(One shot)output mode, F(Deviation)output mode.
- Comparative value(HH, H, L, LL) can be set as LL<L<H<HH in B output mode and the other outputs can be operated separately in output (S, H, L, I) mode regardless of comparative (HH, H, L, LL) set value

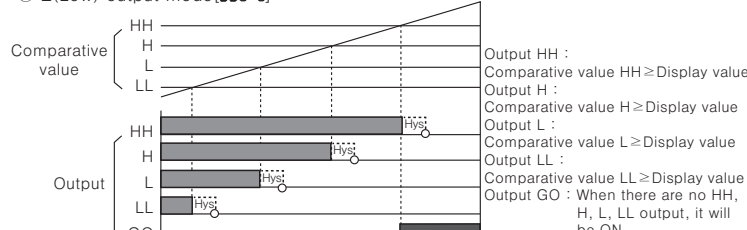
**S(Standard) output mode[StAr-d]**



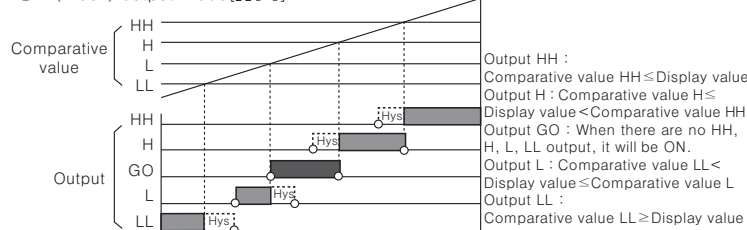
**H(High) output mode[out-h]**



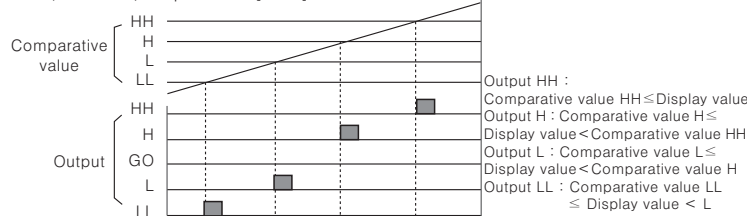
**L(Low) output mode[out-L]**



**B(Block) output mode[out-b]**



**I(One Shot) output mode[out-I]**

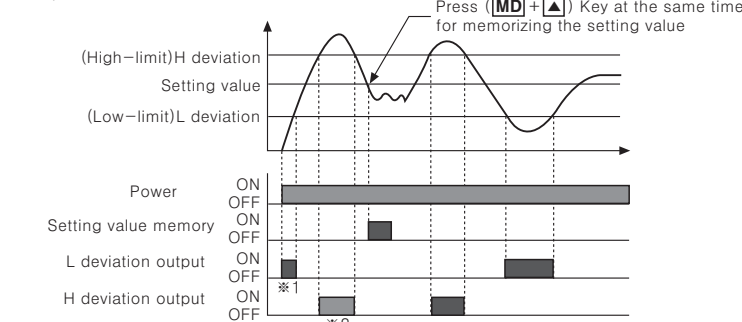


\*There is no GO output in output I mode.  
\*One Shot(■) output time has been fixed 0.3sec.  
\*There is no Hysteresis in I(One shot) comparative output mode.

**F(Deflection) output mode[out-F]**

This function is to memorize the setting value and provide outputs when it exceeds the deviation of H, L.

- The setting value memory : Memorize the current display value as the setting value by pressing **[MD]+[▲]** key in front.
- Display the setting value : Check the memorized setting value by **[▲]** key. (Display the memorized setting value for pressing **[▲]** key continuously.)
- Deviation setting : Set H, L deviation by setting value.
- Deviation setting range : 0.0001 to 99999(The setting range will be changed by decimal point setting parameter. If set decimal point as 0000.0, the setting range will be 0.1 to 9999.9.)
- Operation



\*1 : When select the comparative output limit function, output will not be come.  
\*2 : Output position may different from above graph as output coming under assuming the setting value memory point on above graph.  
\*There are no HH, GO, LL outputs in F output mode.  
\*Even though you set the deviation as "0(Zero)", it will actually work as setting "1".

**Operation chart by each Parameter group**

●The display parameter are different by each operation mode, please see "Parameter".

- : When select the operation mode, the parameter will be displayed.
- X : When select the operation mode, the parameter will not be displayed.

**Parameter 0 group**

Parameter 0	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
PSt.hh		●	●	●	●	●	●	●	●	●	●	●	●	●
PSt.h		●	●	●	●	●	●	●	●	●	●	●	●	●
PSt.L		●	●	●	●	●	●	●	●	●	●	●	●	●
PSt.LL		●	●	●	●	●	●	●	●	●	●	●	●	●
h.PEY		●	●	●	●	●	●	●	●	●	●	●	●	X
L.PEY		●	●	●	●	●	●	●	●	●	●	●	●	X

**Parameter 1 group**

Parameter 1	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
nodE		●	●	●	●	●	●	●	●	●	●	●	●	●
In-A		●	●	●	●	●	●	●	●	●	●	●	●	●
In-b		X	●	X	X	X	●	●	●	●	●	●	●	●
out-t		●	●	●	●	●	●	●	●	●	●	●	●	X
hys		●	X	X	X	X	●	●	●	●	●	X	X	X
GuAr-d	F.dEFY	●	●	●	●	●	●	●	●	●	●	●	●	X
	StAr.t	●	●	●	●	●	●	●	●	●	●	●	●	X
Auto.A		●	X	X	●	X	X	●	●	●	●	X	X	X
Auto.b		X	X	X	X	X	X	●	●	●	●	X	X	X
nEo		X	X	X	X	X	X	X	X	X	X	X	X	●

\*"O" : IN-b sensor will be set as nPn, h, F or PnP, h, F in mode F11, F12, F13.

**Parameter 2 group**

Parameter 2	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
PbAr.t		●	●	●	●	●	●	●	●	●	●	●	●	●
dot		●	●	X	X	X	X	●	●	●	●	●	●	●
tonE		X	X	●	●	●	●	X	X	X	X	X	X	X
PSt.hh		●	●	●	●	●	●	●	●	●	●	●	●	●
PSt.h		●	●	●	●	●	●	●	●	●	●	●	●	●
PSt.L		●	●	●	●	●	●	●	●	●	●	●	●	●
PSt.LL		●	●	●	●	●	●	●	●	●	●	●	●	●
PStAR	*1	●	X	●	X	X	●	●	●	●	●	●	●	●
PStAY	*1	●	●	X	●	X	X	●	●	●	●	●	●	●
PStbH		X	X	X	X	X	X	●	●	●	●	X	X	X
PStbY		X	X	X	X	X	X	●	●	●	●	X	X	X
dI SP.t		●	X	X	X	X	X	●	●	●	●	X	X	X

\*1 : PSt.h, PSt.L, PSt.LL, PStAR, PStAY are displayed in mode F1, F2, F4, F11, F12, F13.

**Parameter 3 group**

Parameter 3	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
F5-h														
F5-L														
Addr														
bPS														
rEo.t														
LoC		●	●	●	●	●	●	●	●	●	●	●	●	●

**Monitoring delay function operation chart by each output mode**

out-t	StAr-d	out-h	out-L	out-b	out-I	out-F
Comparative output adjustment function.	●	X	X	●	X	●
Starting correction timer function	●	●	●	●	●	●

**Parameter**

**Parameter 0 group**

Menu and Parameter display	Parameter	Setting range	Setting key
<b>RUN</b> → <b>PSt.hh</b> → <b>99999</b>	Set HH comparative value	●F1, F2, F7, F9, F11, F12, F13 : 0 to 99999	◀ : Move the setting digit ▼, ▲ : Change the setting value [MD] : Fix and move to the next parameter
→ <b>PSt.h</b> → <b>99999</b>	Set H comparative value		
→ <b>PSt.L</b> → <b>00000</b>	Set L comparative value		
→ <b>PSt.LL</b> → <b>00000</b>	Set LL comparative value		
→ <b>h.PEY</b> → <b>99999</b>	Display high peak value among measuring values		●Reset If you press [MD] key for 2sec. while <b>h.PEY</b> or <b>L.PEY</b> is flickering, the Peak value display will be reset to the current measuring value and it will keep flickering. [MD] If you touch once again, it will return to <b>L.PEY</b> or <b>RUN</b> .
→ <b>L.PEY</b> → <b>-19999</b>	Display low peak value among measuring values		

\*1 : If you press [MD] key in **RUN** mode, it will enter into **PSt.hh**(F output mode:**PSt.h**) at comparative output mode and **h.PEY** at indication type.  
\*When entering into parameter 0, the parameter and data will be flickering by 1 sec. then moving the setting digit and changing the setting value are available.  
\*It will show the set data to flicker by 1sec., then move to next Parameter with touching [MD] key once.

**Parameter 1 group**

Menu and Parameter display	Parameter	Setting range	Setting key
<b>RUN</b> → <b>PRr.A</b> → <b>nodE</b> → <b>nodE F1</b>	This is parameter 1 group.		
→ <b>nodE</b> → <b>nodE F1</b>	Select operation mode.	<b>F1 to F13</b>	▼, ▲ : Change the setting mode → <b>F1 → F2 to F13</b> [MD] : Fix and move to the next parameter
→ <b>In-A</b> → <b>In-A nPn.hF</b>	Set the sensor type of input A.	●PNP transistor output type : <b>PnP.hF</b> ●Contact output type(L output) : <b>PnP.LF</b> ●NPN transistor output type : <b>nPn.hF</b> ●Contact output type(H output) : <b>nPn.LF</b>	▼, ▲ : Change the sensor type [MD] : Fix and move to the next parameter
→ <b>In-b</b> → <b>In-b nPn.hF</b>	Set the sensor type of input B.		
→ <b>out-t</b> → <b>out-t StAr-d</b>	Select the output mode. *1	<b>StAr-d / out-h / out-L / out-b / out-I / out-F</b>	▼, ▲ : Change the setting mode → <b>StAr-d → out-h → out-L / out-F → out-I → out-b</b> [MD] : Fix and move to the next parameter
→ <b>hys</b> → <b>hys 0001</b>	Set the hysteresis for the output. *2	<b>0 to 9999</b> (If decimal point is set in <b>0000.0</b> , the range will be <b>0 to 9999</b> .)	◀ : Move the setting digit ▼, ▲ : Change the setting value [MD] : Fix and move to the next parameter
→ <b>GuAr-d</b> → <b>GuAr-d F.dEFY</b> ↔ <b>GuAr-d StAr.t</b>	Select the start compensating timer function or comparative output(L, LL) limit function. *3	① <b>F.dEFY / StAr.t</b> ② When select <b>StAr.t</b> When <b>[StAr.t 999]</b> is flickering by 1sec. cycle, set the starting correction time <b>0.0 to 999</b> .	① ▼, ▲ : Change the setting mode [MD] : Fix and move to the next parameter ② ◀ : Move the setting digit ▼, ▲ : Change the setting value [MD] : Fix and move to the next parameter
→ <b>Auto.A</b> → <b>Auto.A 99999</b>	Set the Auto-zero time of INA input.	<b>0.1 to 99999</b>	◀ : Move the setting digit ▼, ▲ : Change the setting value [MD] : Fix and move to the next parameter
→ <b>Auto.b</b> → <b>Auto.b 99999</b>	Set the Auto-zero of INB input.	<b>0.1 to 99999</b>	◀ : Move the setting digit ▼, ▲ : Change the setting value [MD] : Fix and move to the next parameter
→ <b>nEo</b> → <b>nEo OFF</b>	It sets the memory retention. The measuring value will be memorized when the power off. (Mode F13 only)	<b>on</b> : Memory retention <b>off</b> : No memory retention	▼, ▲ : Change the setting mode → <b>on → off</b> [MD] : Fix and move to the next parameter <b>nodE</b> .

\*If press [MD] key for 3 sec. in **RUN**, it will enter into parameter 1 group.  
\*1 : It will not be displayed in indication type.  
The output mode is fixed as **out-h** type in F13 operation mode.  
\*2 : Hysteresis operation mode is able to be set in F1, F7 to F10 operation mode.  
\*3 : You are able to select the comparative output limit function or starting correction timer in monitoring delay function mode.  
When selecting the comparative output limit function, it will move to the next parameter **[Auto.A]** and when selecting the starting correction timer **[StAr.t]** you need to be set the starting correction time **[0.0 - 999]** so that it moves to the next parameter **[Auto.A]**.  
\*If press [MD] key for over 2 sec. in every setting mode, data will be set and return to **RUN**.  
\*When entering into parameter 1 group, the parameter name and data will be flickering by 1 sec. then move setting digit by [MD] key or change the setting value by [MD] key.  
\*All data set by users will be shown[displayed] to 1sec. cycle then move to the next parameter by pressing [MD] key.

